Grain refinement of pure Ti during plastic deformation

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1. Introduction

One efficient technical route to strengthen metals is microstructural refinement by plastic deformation. Using severe plastic deformation methods such as equal channel angular pressing and high pressure torsion, the structural length scales of most metals can be easily reduced into the sub-micrometer range\textsuperscript{[1–6]}. By contrast, the exploratory friction-stir experiment\textsuperscript{[7]} and surface mechanical attrition treatment (SMAT)\textsuperscript{[8–11]} may effectively reduce the structural length scale to 10–50 nm. Analysis of the active deformation mechanisms is a crucial step in clarifying the hardening behavior associated with grain refinement\textsuperscript{[1,2,7–15]}.

Titanium and its alloys have increasingly wide applications in aerospace, automotive, power generation (turbine engine) and biomedical areas. Reduction in grain size significantly increases the strength and hence extends applications that require reliable performance. The grain refinement mechanisms of Ti is, however, still unclear due to lack of systematic observations of deformation structures\textsuperscript{[16–23]}. For example, a dynamic recrystallization (DRX) process is suggested to account for the formation of submicrowized grains\textsuperscript{[16–18]}. The detailed mechanism as to how the recrystallized grains nucleate and grow is not well understood. Further evolution with strain from submicrowized grains to NC grains has not been reported in literature.

2. Experimental procedure

A commercial purity titanium sheet was used in this study. The chemical composition is (wt.\%) 0.007 C, 0.0013 H, 0.08 O, 0.030 Fe, and Bal. Ti. The starting sample, 1 mm thick and 80 mm in diameter, was annealed to have equiaxed grains with a mean grain size of 40 \(\mu\)m.

The SMAT set-up and procedure have been described in detail elsewhere\textsuperscript{[8,9]}. The technique is based on the vibration of spherical shots using high-energy ultrasound. Stainless steel shots were placed at the bottom of a cylinder-shaped vacuum chamber that was vibrated by a generator, with which the shots were resonated. Because of the high vibration frequency of the system, the sample surface was peened by a large number of shots. As a consequence, repeated multidirectional peening at high strain rates produces severe plastic deformation in the surface layer. In this work, the sample was treated by shots of 4 mm in diameter at a frequency of 20 kHz for 15 min at room temperature. Note that both the imposed strain and the strain rate have a gradient distribution and the approximate strain rate is \(10^{2–3} \text{s}^{-1}\) near the treated surface.

The present work aims at studying the grain refinement mechanism in Ti by plastic deformation to ultrahigh strains. The special attention is paid to the details of DRX process so as to clarify the formation of submicrowized and NC grains. Deformation twinning is not included in the present study due to the fact that deformation twinning occurs first at low strains and that dislocation slip takes over at high strains and is responsible for the grain refinement\textsuperscript{[16]}.
TEM observation was carried out to clarify the deformation structures in the treated layer. The grain size gradient in the layer appears due to a gradient in the imposed strains and strain rates along the depth, from very large (top surface layer) to zero (strain-free matrix) during the SMAT process [8,9]. Hence, deformation structures of various length scales can be obtained in the deformed surface layer along the depth from the treated surface to the strain-free matrix, i.e. from nano-sized grains to submicrosized and microsized crystallites. As such, the evidence for grain refinement at different strains and strain rates can be obtained. The cross-sectional thin foils for TEM observations were prepared by means of standard sample preparation protocols such as cutting, grinding, dimpling and a final ion thinning at a low temperature.

3. Experimental results

3.1. Formation of slip bands and dislocation-free cells

Fig. 1(a) is a TEM micrograph showing the sharply defined slip bands at low strains (∼100 μm deep below the top surface). The slip bands consist of several elongated subgrains of about several microns in length. The selected area electron diffraction (SAED) pattern (inset) shows some small arcs, indicating small misorientations among these subgrains. The slip bands, aligned along the [1 1 2 0] direction, result from dislocation slip on the basal planes. In particular, the slip bands are observed to occupy ∼80% of the area observed, indicating the dominant role of slipping at low strains. The dislocation density in the slip bands increases with strain, as shown in SB1 of Fig. 1(b). The source of dislocations seems to lie mainly at the subgrain boundary as indicated by arrows. Later on and with increasing strain, the cells start to appear in the interior of the slip bands with increasing dislocation density, as shown in Fig. 1(c). The interior of the cells is nearly dislocation-free, e.g. the cell marked by A; whereas the boundary of cells consists of tangled dislocations of high density.

3.2. Migration dynamic recrystallization (m-DRX)

Fig. 2(a) shows the presence of a segment of high-angle grain boundary (HAGB) (∼80 μm deep below the top surface of the specimen). The HAGB is of sharp contrast as indicated by an arrow. The HAGB originates from the cell boundary, i.e. tangled area of high density dislocations and increases its length with strain. It is interesting to note that the HAGB seems to migrate along the arrow direction, i.e. from the cell interior to the area of high-density dislocation, and the area that the boundary passes through is nearly dislocation-free. In Fig. 2(b), the more parts of HAGBs form as indicated by several arrows and hence, the grain contour becomes visible due to the GB migration. The interior of the immature grains, labeled A and B, respectively, is of few dislocations, in contrast to nearby areas of high-density dislocations. Therefore, the classical DRX, viz., migration DRX (m-DRX) mechanism operates [24–27], which is characterized by the movement of preexisting HAGBs through the deformed microstructure, leaving a strain free region in their wake.

Fig. 2(c) shows one completely recrystallized equiaxed grain, labeled A, in the slip bands. Clearly, this submicrosized grain is dislocation-free. Fig. 2(d) shows the formation of submicrosized grains in the interior of the slip bands due to m-DRX at this stage of strain (∼80 μm deep below the top surface). Many grains become nearly equal-axed, with sharp grain boundaries as indicated by several arrows. Such features are normal after m-DRX.

3.3. Rotation dynamic recrystallization (r-DRX)

The above recrystallized grains may again accumulate dislocations of high density in their interiors due to repetitive deformation as shown in Fig. 3(a). The non-uniformly, tangled dislocations of high density are visible in this figure. With increasing strain, the more refined deformation structure appears, mostly having sizes smaller than 100 nm, as shown in Fig. 3(b). It is interesting to note that the SAED pattern still consists of small arcs, suggesting small misorientations. This indicates the presence of subgrains with low-angle grain boundaries. Fig. 3(c) shows the formation of NC grains with well-defined grain boundaries (∼40 μm deep below the top surface). In comparison with the diffused feature of Fig. 3(b), the
grains are now much easier to resolve. Inset of Fig. 3(c) is the SAED pattern. A set of distinctive continuous rings is observed instead of scattered spots or arcs, indicating the existence of highly misoriented grains. The grain sizes span a range, but are definitely in the nanometer regime. Moreover, the crystallites have sizes similar to those in Fig. 3(b). The average grain size was measured using the linear intercept method to be 58 nm based on statistics over 180 grains. Therefore, from these observations we can infer that the continuous, rotation DRX (r-DRX) operates [24,25,28]. This mechanism involves the gradual rotation of subgrains with increased plastic strain. Eventually the misorientation between neighboring subgrains is sufficiently large that the subboundaries are turned into HAGBs.

One peculiar microstructural feature is shown in Fig. 4. The individual cells have gone through a large shear along a single slip plane, by the presence of a microscopic shear plane extending over several cell boundaries (indicated by arrows). This points to grain boundary sliding that often occurs during superplastic deformation at high temperatures. This feature was typically observed quite frequently in the area of tangled dislocations of high density. The arrow indicates the direction of grain boundary migration. (b) Formation of immature grains, labeled A and B, respectively, via migration of previously-formed grain boundary as indicated by arrows. (c) Completely recrystallized grain labeled A in slip bands. (d) Submicrosized structure after migration DRX.

4. Discussion

Based on the evolution of the deformation structure described above, it is assumed that two DRX processes play important roles in the process of grain refinement of Ti during plastic deformation, leading to the formation of submicrosized and NC grains, respectively.

For the m-DRX, as shown in Fig. 2(a), the cell boundary and other areas as well with high population dislocations are probably the prerequisite for direct nucleation of a segment of HAGB. Hence, the m-DRX, normally a high-temperature phenomenon, can be triggered at low homologous temperatures only if a very large accumulated strain (or a critical stored energy) is reached. The initial size for the HAGB formation may be only a few nanometers, but the segment of HAGB may lengthen and migrate rapidly with increasing strain. According to our TEM observations, the m-DRX seems to initiate when a critical strain, \( \epsilon_{G} \), is reached. In other words, in this case, the critical strain is translated a certain depth of the treated layer. Barnett proposed two dimensionless terms to evaluate the critical condition for the onset of m-DRX [26], i.e., \( \Theta = MG^2/\gamma k^2 \) and \( \Omega = (\sigma/G)^3 \), where \( M \) is the boundary mobility during recrystallization, \( G \) is the shear modulus, \( \gamma \) is the surface energy per area of grain boundary, \( \dot{\epsilon} \) is the strain rate, \( \sigma \) is the flow stress. The former reflects the roles of boundary mobility (\( M \)) and the time (through \( \dot{\epsilon} \)) available for the reaction and the latter reflects the stored energy driving it (through \( \sigma/G \)). During m-DRX, the dynamically recrystallized grain size, \( D \), is determined by a dynamic balance between kinetics of nucleation and kinetics of grain growth. \( D \) is inversely proportional to the strain rate, i.e., \( D = (M(G\dot{\epsilon})/\sigma/G)^2 \), where \( c \) is a constant, \( \dot{\epsilon} \) is the mean subbound grain boundary misorientation [26]. Hence, high strain rate not only promotes m-DRX, but also reduces the steady-state grain size.

On the other hand, the recrystallized submicrosized grains will experience further straining. As such, high-density dislocations are generated (Fig. 3a), which evolve into cells and subgrains (Fig. 3b). Approaching to the top surface during the SMAT process, both strain rates and strains increase significantly [8,9]. The increase in strain rate will increase dislocation density at a given level of strain [30,31]. High strain rates promote the rotation of subgrains and dislocation cells as well. Therefore, the continuous r-DRX begins to operate, involving the gradual rotation of subgrains and cells. The higher strain rates raise the misorientation across adjacent substructures up to a higher value than lower strain rate [22]. Hence, it is reasonable that the subgrains act as precursors of DRX nuclei.

As the HAGBs are formed by progressive increase of misorientation, it is reasonable that the subgrains act as precursors of DRX nuclei.
mechanism. Meyers et al. [28] observed and modeled the process of r–DRX in adiabatic shear localization in a stainless steel. Also, TEM examinations clearly indicate the importance of grain boundary rotation in microstructural evolution. Hence, r-DRX operates in the final stage of grain refinement process, leading to the NC formation.

Remarkably, as shown in Fig. 4, the presence of microscopic glide planes in some grains may be regarded as clear evidence for grain boundary sliding at room temperature deformation. It indicates that high strain rate promotes the microscopic boundary sliding [29], contributing to the deformation, similar to superplastic deformation which is usually observed at high temperatures.

5. Conclusion

The grain refinement behavior was studied in Ti during SMAT. The evolution of deformation structure allows detailed investigation of the DRX phenomena upon deformation. Strain and strain rate are found to affect the grain refinement processes. In summary, the experimental results and their interpretation allow us to come to the following conclusions:

(1) The deformation structures form by the sequence of slip bands with elongated subgrains, tangled dislocations of high density and cell structures, respectively, at low strains.

(2) By the nucleation and migration of high-angle grain boundary inside slip bands with increasing strain, the classical, migration dynamic recrystallization starts to operate at a critical strain, leading to the formation of submicrosized grains.

(3) Upon further plastic deformation, the recrystallized submicrosized grains lead to further breakup by the formation of subgrains. The nanocrystallites form mainly due to a continuous, rotation dynamic recrystallization mechanism. That is, by the progressive increase of GB misorientations at large strain at high strain rate.

(4) The formation of arrays of coplanar grain boundaries confirms a deformation mechanism of cooperative grain boundary sliding.

Acknowledgements

This research received backing from NSF of China Grant No. 10721202 and 973 Project Grant Nos. 2010CB631004.

References