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Stress evolution in elastic-plastic electrodes during electrochemical processes: A numerical method and its applications



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ABSTRACT

Monitoring in real time the stress state in high capacity electrodes during charge-discharge processes is pivotal to the performance assessment and structural optimization of advanced batteries. The wafer curvature measurement technique broadly employed in thinfilm industry, together with stress analysis using the Stoney equation, has been successfully adopted to measure in situ the stress in thin film electrodes. How large plastic deformation or interfacial delamination during electrochemical cycles in such electrodes affects the applicability of Stoney equation remains unclear. Here we develop a robust electrochemical-mechanical coupled numerical procedure to investigate the influence of large plastic deformation and interfacial failure on the measured stress in thin film electrodes. We identify how the constitutive behavior of electrode materials and film-substrate interfacial properties affect the measured stress-capacity curves of electrodes, and hence establish the relationship of electrode material parameters with the characteristics of stress-capacity curves. Using Li-ions batteries as examples, we show that plastic deformation and interfacial delamination account for the asymmetric stress-capacity loops seen in in situ stress measurements. The methods used here, along with the finite-element code in the supplementary material, may be used to model the electrode behavior as a function of the state of charge.

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1. Introduction

High charge capacity anode materials like Si and Sn have attracted great interests in recent years (Bourderau et al., 1999; Liang et al., 2014; Huggins, 1999; Winter and Besenhard, 1999). One major tradeoff arisen from the high capacity is the resulted high stress. Lithiation and de-lithiation in anode materials inevitably result in huge volume expansion and contraction, lead to high internal stresses and, thus, poor cycle life of high capacity anode batteries (Shi et al., 2016; Klinsmann et al., 2016; Zhang et al., 2016). Many strategies were proposed to prolong the service duration of anode materials. One popular approach was to optimize the microstructure of the materials (Szczech and Jin, 2011; Zhang et al., 2017) to alleviate internal stress induced by volume expansion. To examine the effectiveness of such structural optimization, we desire to have

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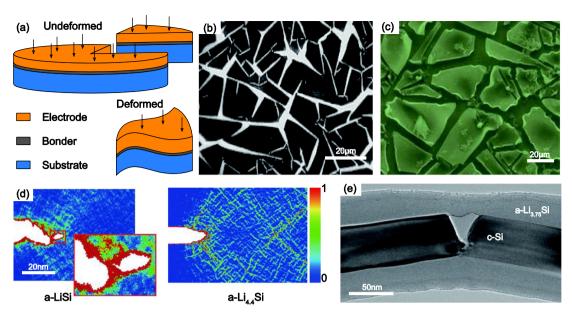


Fig. 1. Illustrations of high capacity battery electrodes undergone large deformation and interfacial failure: (a) A film-bonder-substrate system for in situ curvature monitoring. (b) Optical micrograph showing micro-cracks in amorphous silicon thin film electrode after charge and discharge. (c) SEM picture to show interfacial delamination and cracking in the thin film electrode after a certain amount of cycles (b and c, Courtesy of Yang et al., 2018). (d) Molecular dynamic simulations showed brittle to ductile transition, with cavitation dominated failure in low lithium concentration amorphous silicon (left) versus micro-shearing in high lithium concentration amorphous silicon (right, Courtesy of Ding et al., 2015). (e) Experimental observation on ductile deformation in amorphous silicon with high lithium concentration against brittle fracture in crystalline silicon (Courtesy of Wang et al., 2015).

an accurate and real time measurement of stress in high capacity electrodes (Sethuraman et al., 2010, 2012; Duan and Wei, 2017). Real time stress is also indispensable to better our understanding about the electrochemical-mechanical processes and is helpful for faithful model development for electrode materials.

Stresses in thin film electrodes may be measured by monitoring the bending of the electrode-substrate bilayer and using the Stoney equation. A typical battery setup for such in situ stress measurement is shown in Fig. 1a, which consists of a thin film, a bonder layer, and a substrate. Using this method, Sethuraman et al. (2010, 2012) showed how stress changes in Si- and graphite-based anode film materials during charging and discharging. Later on, Soni et al. (2011) and Haftbaradaran et al. (2012) used the same method to investigate the stress-capacity behavior of patterned electrode islands, aimed to illustrate the influence of interfacial failure between electrode islands and the substrate on capacity degradation (He et al., 2012). Recently, Pharr et al. (2016) measured stresses in sputter-deposited amorphous Ge thin films as the electrode material. The stress-capacity curves from different research groups all showed a hysteresis loop, which was caused by irreversible deformation during charge-discharge cycles. In addition, the electrode-substrate interface may be subjected to excessive deformation and may fail during cycling. According to the in situ tests, fracture and delamination of the film electrode from substrate, as shown in Fig. 1b, were broadly observed (e.g., Maranchi et al., 2006; Yang et al., 2018). Such interfacial deformation will inevitably influence the stress-capacity curve. Connecting the properties of the interface and the anode material with the measured curvature-capacity curve is hence crucial to determine the actual stress in the electrode material. More importantly, we may use the curvature-capacity curves to extract the interface and material properties.

A typical route to obtain material parameters in constitutive models is to compare the predicted stress-capacity response from the models with available experimental data. Following this strategy, different groups have developed constitutive models and the numerical methods for electrode materials to decipher the materials' properties from the stress-capacity response. For example, Bhandakkar et al. (2010) compared the stress-capacity curves of Sn films from numerical analysis and experimental data, and estimated the interfacial strength. Zhao et al. (2012) and Pharr et al. (2013) studied the mechanical properties of electrode materials using first-principle calculations, and compared their results with measured stress-capacity curves. Jia and Li (2016) and Wen et al. (2018) explored the influence of concentration-dependent elasticity on stresses in spherical particles and film-substrate structures, respectively. Zhao et al. (2011, 2012) and Brassart et al. (2013) reported how the electrode materials' plastic flow and shakedown were related to the characteristics in the stress-capacity curves. Bower et al. (2011) predicted the evolution of stress and potential for a one-dimension Li-ion half-cell with a Si anode by considering finite strain, plastic flow, and electric current flow. By taking an analogy between diffusion and heat conduction, Yang et al. (2014) presented a chemical-mechanical model to investigate the lithiation-induced phase transformation, morphological evolution, stress generation and fracture in crystalline silicon nanowires. Levitas and Attariani (2014) analyzed the anisotropic compositional expansion in elastic-plastic anode materials. The work by Anand (2012), Di Leo et al.

(2014) and Chester et al. (2015) coupled Cahn-Hilliard-type diffusion with large elastic-plastic deformation for anode materials' diffusion-induced swelling for lithium-ion batteries and applied the model to phase-separating problems.

Since the reliability of a stress-capacity curve depends on the applicability of the Stoney equation for in situ measurement (Stoney, 1909), it is important to know how the deformation mechanisms in the materials and the interfaces affect those curves. It is known that large deformation and interfacial failure are not taken into account by the Stoney equation. Concentration-dependent material parameters will make theoretical modeling more difficult. Physically-based constitutive models, combined with robust numerical methods, may help surmount many of these challenges. In this paper, we first present a robust numerical procedure and its finite element implementation in Section 2. The elastic-plastic constitutive equations for diffusion-induced stresses are also shown in Section 2. In Section 3, we show how lithium concentration-dependent elastic-plastic properties affect the stress-capacity curves of thin film batteries. In Section 4, we demonstrate the influence of the interfacial delamination on the stress-capacity of thin film electrodes. We conclude in Section 5 with final remarks and discussions.

2. The theoretical model

If the anode material is crystalline, phase change may occur within the first few cycles till the anode material transforms to an amorphous state. That is commonly seen in Si anodes. Several groups have developed constitutive models to capture the associated electrochemical-mechanical processes (Bower et al., 2011; Anand, 2012; Di Leo et al., 2014; Chester et al., 2015), and the physical processes taken into account include (1) the diffusion mechanism governed by concentration and electric field, (2) concentration variation induced volume change, (3) concentration associated with elastic-plastic deformation, and (4) stress resulted from deformation. In this paper, we aim to add more physical mechanisms by accounting for (a) concentration dependent flow stress, (b) competition between plasticity in the electrodes and deformation at the interfaces between electrodes and substrates, and (c) effects of electrode plasticity and interfacial failure on stress measurement using the Stoney equation. We are motivated to taking these mechanisms into consideration by recent experimental observations, as seen in Fig. 1b–e. In particular, the results from Fig. 1d and e suggest the need for the concentration-dependent elastic-plastic behavior of electrode materials. An open source and robust finite-element procedure is provided for small elastic yet large plastic deformation occurring in most high capacity anode materials. The model is implemented in the commercial FE package ABAQUS (ABAQUS/Standard, 2013) as a user-element (See supplementary material). The numerical method can also be applied for nearly incompressible anode materials, which can be used for any complex structure, like nanowire (Chan et al., 2008) and nano-island (Soni et al., 2011; Duan and Wei, 2017).

2.1. Governing equations

In an anode material during changing (discharging), the governing equations, associated with electrochemical reaction and mechanical deformation, are presented here.

1. The local force balance equation: It is assumed that the chemical reaction rate is much slower than stress waves, and hence we have force equilibrium in the form of

$$\frac{\partial \sigma_{ij}}{\partial x_j} = 0,\tag{1}$$

where σ_{ii} is the Cauchy stress at a material point x_i .

2. The diffusion equation: At any time t, the lithium concentration $\phi(x, t)$ at a material point x_i in the electrode structure of volume v is governed by the diffusion equation (Carslaw and Jaeger, 1959)

$$\frac{\partial \boldsymbol{\phi}}{\partial t} + \nabla \cdot \boldsymbol{J} = 0 \tag{2a}$$

The concentration and flux boundary conditions are respectively given as

$$\phi = \tilde{\phi} \text{ on } \Gamma_1 \text{ and } \boldsymbol{J} \cdot \boldsymbol{n} = l_i n_i = -l^s \text{ on } \Gamma_2,$$
 (2b)

where the sum of Γ_1 and Γ_2 represents the overall surface of the volume v, and n is the surface normal of Γ_2 , and f is the surface flux. The galvanostatic current boundary condition f is related to the current density i^s via f is f is related to the current density f via f is f in the surface flux. The galvanostatic current boundary condition f is associated with compound phase f in the electrode where f and f indicates the lithium and the anode electrode material, respectively, and the subscript f indicates the lithium fraction ranging from 0 to f in the maximum lithium fraction f is known as f in the electrode material, respectively, and the subscript f indicates the lithium fraction ranging from 0 to f in the maximum lithium fraction f is known as f is known as f in the electrode material, f is known as f in the electrode material, f is f in the subscript f in the electrode material, f is f in the electrode material, f is f in the subscript f in the electrode material, f is f in the electrode material, f in the electrode material, f is f in the electrode material, f in the electrode material, f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material f is f in the electrode material f in the electrode material

$$\phi = \frac{\psi}{V_{\psi} N_a},\tag{3}$$

where V_{ψ} is the volume of the compound $A_{\psi}B$ and is a function of ψ , and N_a is Avogadro's number. Taking the lithiumsilicon battery system as an example, we may write the volume of the compound $Li_{\psi}Si$ as (Fan et al., 2013; He et al., 2012)

$$V_{\psi} = \left(1 + 3.2 \frac{\psi}{\psi_{max}}\right) \times 10^{-28} \text{ m}^3. \tag{4}$$

Considering ψ as a continuous variable, we can rewrite the diffusion equation in terms of ψ as

$$\frac{V_{\psi} - \psi V_{\psi}'}{V_{\omega}^{2} N a} \frac{\partial \psi}{\partial t} + \nabla \cdot \mathbf{J} = 0 \ (in \ v). \tag{5}$$

3. The constitutive relationship for the Li-ions flux: The Li-ions flux J is commonly used as a function of the gradient of a stress-dependent chemical potential μ (Li, 1978; Yang, 2005; Zhang et al., 2008)

$$\boldsymbol{J} = -\frac{D(\boldsymbol{\phi}, \boldsymbol{x})}{RT} \nabla \mu(\boldsymbol{\phi}, \sigma_h, \boldsymbol{x}, t). \tag{6}$$

As the exact dependence of μ on σ remains debatable, we adopt a simple form (Wei et al., 2010)

$$\mu(\phi, \sigma_h, \mathbf{x}, t) = \mu_0 + RT \ln \frac{\phi}{\phi_{max}} - \Omega \sigma_h, \tag{7}$$

where μ_0 is the referential potential, ϕ_{max} is the maximum lithium concentration and Ω the lithium ions partial molar volume and σ_h the hydrostatic stress, i.e., $(\sigma_{xx} + \sigma_{yy} + \sigma_{zz})/3$. The second term represents an entropic contribution to the free-energy, while the third term is the work done by the applied stress. Combining Eqs. (6) and (7), the flux equation can be reformulated as

$$\boldsymbol{J} = -\frac{D(\boldsymbol{\phi}, \boldsymbol{x})}{\boldsymbol{\phi}} \nabla \boldsymbol{\phi}(\boldsymbol{x}, t) + \frac{D(\boldsymbol{\phi}, \boldsymbol{x})\Omega}{RT} \nabla \sigma_{h}. \tag{8}$$

We consider a linear dependence of the diffusivity on concentration and assume isotropic diffusion in amorphous electrode materials, $D(\phi, \mathbf{x}) = D_0 \phi$.

4. The constitutive relationship for the Cauchy stress: The rate-independent elastic-plastic constitutive relationship (coupled with diffusion) in the incremental form is then given as

$$d\sigma_{ij}^{J} = C_{ijkl} d\varepsilon_{kl}^{e}, \tag{9}$$

where $d\sigma^{J}_{ij}$ is an objective increment of the Cauchy stress, and C_{ijkl} is the fourth-order elastic modulus tensor, which depends on the lithium concentration ψ . Note that the elastic strain is small for most high capacity anode material and the amorphous anode material is taken to be isotropic, then C_{ijkl} only depend on Young's modulus $E(\psi)$ and the Poisson's ratio ν . The Young's modulus $E(\psi)$ also varies slightly during the lithiation process (Shenoy et al., 2010; Sethuraman et al., 2010). The usual stretching tensor increment $d\varepsilon^m_{kl}$ can be composed of an elastic deformation part $d\varepsilon^e_{kl}$ and a plastic deformation part $d\varepsilon^p_{kl}$, and $d\varepsilon^m_{kl} = d\varepsilon^e_{kl} + d\varepsilon^p_{kl}$. For small elastic yet large plastic deformation, we used the loading/unloading criterion by accounting for the usual complementarity condition

$$\Phi \le 0, \ \lambda \ge 0, \ \lambda \Phi = 0, \tag{10}$$

where λ is a plastic multiplier and $\Phi(\sigma_{ij}, \bar{\varepsilon}^p)$ is the yield function which depends on both the current stress and the equivalent plastic strain $\bar{\varepsilon}^p$, $\bar{\varepsilon}^p = \int \sqrt{\frac{2}{3}} d\varepsilon_{kl}^{pl} \cdot d\varepsilon_{kl}^{pl}$. We write it in the form of

$$\Phi(\sigma_{ij}, \bar{\varepsilon}^p) = \sqrt{\frac{3}{2} \left(\sigma_{ij} - \frac{1}{3}\sigma_{ij}\delta_{ij}\right) \left(\sigma_{ij} - \frac{1}{3}\sigma_{ij}\delta_{ij}\right)} - \sigma_y(\bar{\varepsilon}^p, \psi). \tag{11}$$

The second term at the right hand side of Eq. (11) indicates that the yield strength is a function of both $\bar{\epsilon}^p$ and the lithium fraction ψ . A bilinear hardening modulus is used here,

$$\sigma_{y}(\bar{\varepsilon}^{p}, \psi) = \sigma_{y0}(\psi) + \frac{E(\psi)E_{t}(\psi)}{E(\psi) - E_{t}(\psi)}\bar{\varepsilon}^{p},\tag{12}$$

where $\sigma_{y0}(\psi)$ is the initial yield stress and $E_t(\psi)$ is the hardening modulus. Using the J_2 flow rule, we have

$$d\varepsilon_{ij}^{pl} = \lambda \frac{\partial \Phi}{\partial \sigma_{ii}}.$$
(13)

Eq. (13) is used to determine the plastic strain increment.

5. Objective variables for finite deformation: The objective stress rate is defined by the Jaumann stress rate (McMeeking and Rice, 1975) as

$$\dot{\sigma}_{ij}^{J} = \dot{\sigma}_{ij} + \sigma_{ik} W_{kj} - W_{ik} \sigma_{kj}, \tag{14}$$

where $\dot{\sigma}_{ij}$ is the time rate of Cauchy stress, $W_{ij} = (L_{ij} - L_{ji})/2$ is the spin tensor, $L_{ij} = \frac{\partial v_i}{\partial x_j} = \dot{\mathbf{F}} \mathbf{F}^{-1}$ is the velocity gradient for $F_{ij} = \frac{\partial x_i}{\partial X_j}$ being the deformation gradient, and $\dot{\sigma}_{ij}^J$ is the Jaumann stress rate, which can then be used to objectively describe the stress and strain rate $(\dot{\varepsilon}_{kl})$ relation. By considering large plastic strain, we take the total logarithmic strain measure $[\boldsymbol{\varepsilon}_{n+1}]$ at time n+1 during the standard interval $[t_n, t_{n+1}]$ by

$$[\boldsymbol{\varepsilon}_{n+1}] = [\boldsymbol{\varepsilon}_n] + [\boldsymbol{\Delta}\bar{\boldsymbol{\varepsilon}}],\tag{15}$$

In Eq. (15), $[\Delta \bar{\epsilon}]$ is a rotation-neutralized strain increment from time t_n to t_{n+1} . Unless stated otherwise, a parameter with a top bar is defined in the rotated coordinate. Hughes (1984) used the approximate 2nd-order calculation for $[\Delta \bar{\epsilon}]$, which is given as

$$[\boldsymbol{\Delta}\bar{\boldsymbol{\varepsilon}}] = [\boldsymbol{R}_{n+1/2}]^T [\boldsymbol{\Delta}\boldsymbol{D}] [\boldsymbol{R}_{n+1/2}], \tag{16}$$

where $\Delta \pmb{D} = sym(\frac{\partial \Delta \pmb{u}}{\partial \pmb{x}_{n+1/2}})$ is the rotation-neutralized stretch increment tensor relative to the neutralized positions $\pmb{x}_{n+1/2} = \frac{1}{2}(\pmb{x}_n + \pmb{x}_{n+1})$, and $[\pmb{R}_{n+1/2}]$ comes from the decomposition of the deformation gradient F_{ij} in the following,

$$F_{ij} = R_{ik}U_{kj}, \text{ and } R_{ji}R_{ij} = \delta_{ij}$$

$$\tag{17}$$

Here \mathbf{R} is a rotational tensor and \mathbf{U} is the right stretch tensor. The updated objective stress defined in the rotated coordinate is given as $[\bar{\sigma}_{n+1}] = [\bar{\sigma}_n] + [\Delta \bar{\sigma}]$. This is a simple yet powerful algorithm for large inelastic deformation. The explicit expression of R_{ij} in terms of quaternion parameters is also available (Hughes and Simo, 1998; Crisfield, 1997).

2.2. Numerical procedures

Now we layout the variational forms of the two partial differential Eqs. (1) and (5) for finite-element implementation.

1 The principle of virtual work δW_m for mechanical deformation and its differentiation $d\delta W_m$ are given as

$$\delta W_m = \int_{\nu} \sigma_{ij} \delta D_{ij} d\nu - \int_{\nu} f_i^B \delta u_i d\nu = 0, \tag{18}$$

and

$$d\delta W_{m} = \int_{\nu} \delta D_{ij} \frac{\partial \sigma_{ij}}{\partial \varepsilon_{kl}^{m}} d\varepsilon_{kl}^{m} d\nu + \int_{\nu} \sigma_{ij} \left(\frac{\partial \delta u_{k}}{\partial x_{i}} \frac{\partial du_{k}}{\partial x_{j}} - 2\delta D_{ik} dD_{kj} \right) d\nu + \int_{\nu} \left\{ \delta D_{ij} \frac{\partial \sigma_{ij}}{\partial \psi} d\psi \right\} d\nu, \tag{19}$$

respectively.

2 The variational form δW_d of the diffusion equation (Eq. (5)) and its differentiation is given, in turn, as

$$\delta W_d = \int_V \delta \psi \frac{V_{\psi} - \psi V_{\psi'}}{V_{\psi}^2 N_a} \frac{\partial \psi}{\partial t} d\nu - \int_V \delta \psi_{,i} J_i d\nu - \int_S J^s \delta \psi ds = 0, \tag{20}$$

and

$$d\delta W_{d} = \int_{\nu} \delta \psi H(\psi) \frac{\partial d\psi}{\partial t} d\nu + \int_{\nu} \delta \psi_{,i} D_{0} H(\psi) d\psi_{,i} d\nu - \int_{\nu} \delta \psi_{,i} \frac{D_{0} \Omega}{RT} \sigma_{h,i} H(\psi) d\psi d\nu - \int_{\nu} [\delta \psi_{,i} G_{,m} du_{m,i} + \delta \psi_{,m} G_{,i} du_{m,i}] d\nu$$
(21)

respectively. Here $H(\psi) = \frac{\partial \phi}{\partial \psi} = \frac{V_{\psi} - \psi V_{\psi}'}{V_{\psi}^2 N_a}$ and $G_{,i} = D_0 H(\psi) \psi_{,i} - \frac{D_0 \Omega}{RT} \frac{\psi}{V_{\psi} N_a} \sigma_{h,i}$. The first three terms on the RHS of Eq. (21) are associated with diffusion, and the last one is resulted from finite deformation.

3. Plastic response in the electrode materials

The film-bonder-substrate system (see Fig. 1a) is a typical structure used for in situ stress measurements during the charge/discharge process. The electrode film adhered to the substrate, when expands or contracts during the charge/discharge process, governs the substrate's curvature evolution. The film's biaxial stress σ_m can be deduced from the substrate's curvature κ using the Stoney equation (Stoney, 1909)

$$\sigma_m = \frac{E_s h_s^2}{6(1 - \nu_s)h_f} \kappa, \tag{22}$$

where E_s and v_s are the substrate's elastic modulus and Poisson's ratio, respectively, and the thickness of the substrate and the film are h_s and h_f respectively. The validity of the above equation is contingent on the following assumptions: (a) $h_f \ll h_s$, (b) h_f remains nearly unchanged during the deformation, and (c) the interface between the film and the substrate is non-deformable and of zero-thickness. Previously, we demonstrated that even for elastic deformation in the electrode film,

comparable h_f and h_s will give rise to significant differences between the true stress in the electrode film and that predicted based on Eq. (22) (Wen et al., 2018). To address the influence of assumptions (b) and (c) on real stress assessment, it is desired to solve the electrochemical-mechanical coupled problems within the finite deformation scheme, consider the plastic response of the elastic-plastic film electrode, and account for possible interfacial deformation.

In mimicking a typical in situ stress measurement, we consider an amorphous silicon film electrode constrained by the substrate with a thickness-radius ratio $\frac{h_s}{R_s} = 0.2$. The thickness of the substrate is $h_s = 60~\mu$ m in the simulation. The electrode film's thickness h_f is rather small, $\frac{h_f}{h_s} = 0.002$. Its elastic modulus varies linearly with the Li-concentration (Shenoy et al., 2010)

$$E_{f} = E_{0} + \frac{\psi(t)}{1 + \psi(t)} m E_{0}, \tag{23}$$

where E_0 is the modulus of pure silicon and m is a coefficient. The initial elastic modulus, the slope and the Poisson's radio are $E_0 = 90.13$ GPa, m = -0.79 and $v_f = 0.22$, in turn. The diffusivity is taken as $D_0 = 1.0 \times 10^{-16}$ m²/s (Pan et al., 2015), and the lithium ions partial molar volume is $\Omega = 3.497 \times 10^{-6} \text{m}^3/\text{mol}$ (Zhang et al., 2007). For the substrate, its elastic modulus and Poisson's radio are $E_s = 162$ GPa and, $v_s = 0.26$ (Brantley, 1973), respectively. We consider a charging condition that a constant current density of $5 \,\mu\text{A/cm}^2$ (ca. C/24 rate) is applied to the top surface of the electrode film, while all other faces are flux free.

3.1. The plastic electrode materials with different hardening behavior

Here we examine how strain hardening in the electrode film affects the stress-capacity curves. We show in Fig. 2a the equivalent stress σ_{ℓ} and equivalent strain ϵ_{ℓ} curves of the electrode material during charge and discharge, where σ_{ℓ} $\sqrt{\frac{3}{2}}(\sigma_{ij} - \frac{1}{3}\sigma_{ij}\delta_{ij})(\sigma_{ij} - \frac{1}{3}\sigma_{ij}\delta_{ij})$ and $\varepsilon_e = \sqrt{\frac{2}{3}}(\varepsilon_{ij} - \frac{1}{3}\varepsilon_{ij}\delta_{ij})(\varepsilon_{ij} - \frac{1}{3}\varepsilon_{ij}\delta_{ij})$, $\delta_{ij} = 1$ if i = j and $\delta_{ij} = 0$ otherwise. The electrode material exhibits bilinear isotropic hardening during charge, and discharge induced unloading is elastic at the beginning, followed by plastic discharge. In Fig. 2b, we show the substrate's curvature κ as a function of ψ from FE calculation. If both the elastic modulus and the initial yield stress of the electrode material are the same (see Fig. 2a), the slopes of the resulted $\kappa-\psi$ response are the same as well in the elastic stage. In contrast, the plastic response in the $\kappa-\psi$ curves and the hysteresis loop area are affected by the hardening modulus E_t . We also observe from Fig. 2b cyclic hardening in different charge/discharge cycles. The hysteresis loop reflects the influence of electrode materials' plastic dissipation on κ . In Fig. 2c, we give the correlation between the curvature 'hardening' (κ_t , the slope of $\kappa-\psi$ curve in the hardening region) and the electrode materials' hardening. We notice that the relationship between K_t/K_e and E_t/E_0 does not follow a linear relationship. Large plastic deformation in the film affects the slope of the $\kappa/\kappa_0-\psi$ curves: greater E_t leads to less plasticity in the electrode material. By comparing the film's biaxial stress from the FEM results and that from the Stoney equation, as shown in Fig. 2d, we see that the Stoney equation overestimates the stress in the film due to the large deformation, especially during large plastic deformation. From Fig. 2e, we also see that the thickness of the electrode film h_f varies significantly as a function of concentration. Furthermore, it accumulates with cycling when we record h_f at the same concentration ψ . The large volume change and resulted film thickness variation account for the deviation of real-time stress in electrode materials from Stoney equation based prediction.

3.2. The elastic-plastic electrode with different initial yield stress

Now we assume that the initial yield stress is proportional to the elastic modulus, that is, $\sigma_{y0} = 5\%E_0$. In Fig. 3a, we extract the stress-strain curve of the film electrode material from the FE model. By changing the initial elastic modulus, we examine the effect of variation in yield stress on the curvature- ψ curve. As shown in Fig. 3b, the slope of the $\kappa - \psi$ curves could be used as a measurement for the elastic modulus of the electrode material (Sethuraman et al., 2010). In Fig. 3c, we also show the averaged Cauchy stress in the electrode at different concentration ψ . During different charge/discharge cycles, there is also cyclic hardening behavior, which is a resultant of the implemented hardening behavior of the electrode material. As shown in Fig. 3d, the curvature at the turning point depends linearly on the initial yield strength. This feature may be utilized to determine the yield strength of electrode materials if one obtains the curvature-capacity curve.

3.3. Predictability against experimental results

As previously discussed, the Stoney equation is not suitable for silicon electrode material which exhibits large plastic deformation. A simple and effective method for getting electrode material properties is to realize a fully coupled electrochemical-mechanics FEM theory, and to adjust electrode material parameters by fitting experimental data. According to the atomistic simulation and experiment results shown in Fig. 1c and d, the properties of electrode materials are sensitive to lithium concentration. The plastic response changes with the state of charge ψ (Fan et al., 2013; Ding et al., 2015; Wang et al., 2015). We take this effect into account and consider the influence of lithium concentration on electrode properties by adopting the Voce model (Voce, 1955). Other models could be conveniently implemented in the current computational scheme. In the Voce model, the yield stress σ_{ν} of the electrode material is now a function of state of charge,

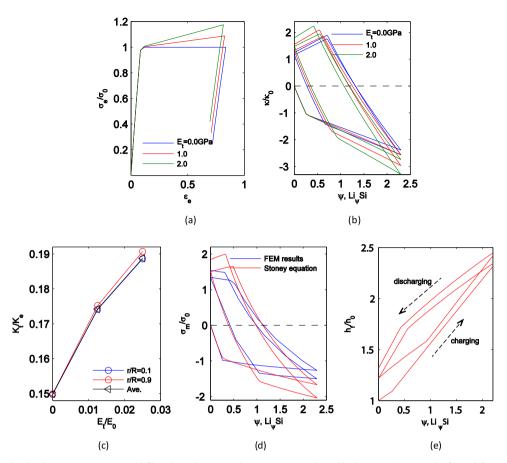


Fig. 2. The calculated substrate's curvature κ and film's biaxial stress evolution σ_m in two charge/discharge cycles using the finite deformation algorithms with different hardening modulus E_t . Here the electrode film is assumed to follow a bilinear isotropic hardening. The Cauchy stress is normalized by the initial yield stress $\sigma_0 = \sigma_y = 5$ GPa. The curvature is normalized by $\kappa_0 = \frac{6(1-\nu_t)h_T^2}{E_th_t^2}\sigma_0$ according to the Stoney equation (Eq. (22)). (a) Different constitutive behavior of the electrode extracted from one material point in the FE model. (b) The average curvature of the substrate vs. ψ along the radius from FE calculations. (c) The slope of the $\kappa/\kappa_0 - \psi$ curves versus the normalized hardening modulus, where $K = \frac{d(\kappa/\kappa_0)}{d\psi}$, and K_t are the slopes of the $\kappa/\kappa_0 - \psi$ curve during the elastic and the plastic stage in Fig. 2b, respectively. (d) The averaged biaxial stress vs. ψ in the film from FE calculations and that from the Stoney equation when $E_t = 2.0$ GPa. (e) The evolution of electrode film's thickness h_f as a function of ψ , in which h_0 is the initial thickness of the film.

$$\frac{\sigma_{y}}{\sigma_{v0}} = 1 + \frac{\psi(t)}{\psi_{max}} R_{0} + R_{\infty} \left[1 - e^{-\frac{\psi(t)}{\psi_{max}} b} \right]. \tag{24}$$

We show in Fig. 4a the described yield stress σ_y of the electrode material as a function of ψ by the Voce model in Eq. (24). The parameters used in the model are given as follows, $\sigma_{y0}=2.0$ GPa, $R_0=0$, $R_\infty=-0.75$, b=5. In Fig. 4b, we compare the experimental results from Sethuraman et al. (2010) with our FEM calculations using the same group of parameters for Fig. 4a. For the simple situation that $R_\infty=0$, the yield stress depends linearly on lithium fraction $\psi(t)$. When $R_0<0$, there is a lithiation softening effect during charging. Indeed, observations on amorphous silicon electrode materials do see perceivable stress-softening behavior (Sethuraman et al., 2010; Soni et al., 2012). For lithiation strengthening materials (Sethuraman et al., 2012; Soni et al., 2012; Ding et al., 2015), we may let $R_0>0$ to capture the effect. Corresponding results are shown in Fig. 4c and d.

4. Interface delamination in the film-substrate structure

In the previous section, we assume that the film electrode is perfectly adhered to the substrate. For high charge ratio electrode materials, the stress on the order of GPa is a serious challenge to the interface (Shi et al., 2016; Yang et al., 2018). Once there is delamination or interfacial sliding between the film and the substrate, the Stoney equation is also not applicable. In this section, we discuss the influence of the interface's plastic dissipation and failure on in situ stress measurements.

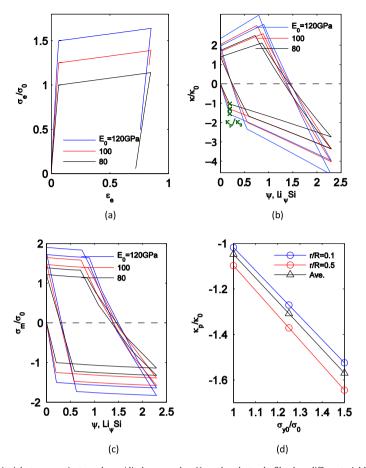


Fig. 3. Curvature κ and film's biaxial stress σ_m in two charge/discharge cycles. Here the electrode film has different yield stress $\sigma_{y0}/E_0 = 5\%$ and hardens linearly with $E_t = 1.0$ GPa. The Cauchy stress and the curvature are normalized by the initial yield stress $\sigma_0 = 5$ GPa and $\kappa_0 = \frac{6(1-\nu_t)h_t}{E_th_t^2}\sigma_0$, respectively. (a) Constitutive behavior of three electrode materials (different E_0) extracted from a material point in the FE model. (b) The average curvature of the substrate vs. ψ along the radial direction from FE calculations. Here κ_p is the curvature at the transitional point due to initial yielding. (c) The averaged biaxial stress vs. ψ in the film from FE calculations. (d) The relationship between κ_p/κ_0 and σ_{y0}/σ_0 .

As seen in Fig. 1a, a cohesive layer bonds the film electrode to the substrate for in situ stress measurement. Ti and Cu are usually used as bonder materials because of their high cohesive properties and large plastic dissipation (Sethuraman et al., 2010; Soni et al., 2012). To investigate the influence of deformation in the cohesive interface on in situ stress measurements, we adopt the 4-node axisymmetric cohesive element in ABAQUS (COHAX4) to simulate interface delamination (ABAQUS/Standard, 2013). Different types of interfacial constitutive model (Needleman, 1990; Xu and Needleman, 1994; Camacho and Ortiz, 1996; Wei and Anand, 2004; Wei, 2014) may be employed. Here we consider the one with normal stress and shear stress response demonstrated in Fig. 5a: the initial response of the cohesive interface is linear, with an elastic stiffness K_n in the normal direction and K_s in the tangential shear direction. Damage starts when either the normal or the shear stress reaches their respective threshold, t_n^{max} and t_s^{max} . During the stage of damage evolution, a scalar variable D represents the overall damage in the interface material. The interface degrades linearly with damage D as it grows from 0 (intact initial state) to 1 (complete failure). Upon unloading, interfacial stress returns to the origin, as illustrated by the dashed line, and the elastic stiffness is multiplied by the factor (1 - D). We consider the case that the initial normal failure strength is significantly greater than the shear strength, with $t_n^{max} = 1$ GPa and $K_n = 100$ GPa. The tangential properties will be given in the particular applications to be presented. The bonder's separation δ is normalized by its initial thickness h_{b0} , which is assumed to be $h_{b0} = 1$ μ m.

4.1. The influence of interface stiffness

We first explore the influence of interface shear stiffness on the curvature-capacity response of a thin film battery. As seen in Fig. 5b and c, the interfacial stiffness K_s/E_0 has a small impact on the slope in the $\kappa-\psi$ response when $K_s/E_0 > 0.1$. Only if $K_s/E_0 < 0.01$ and also nearby the edge of the film (r/R = 0.9), the effect of interface stiffness becomes perceivable. In Fig. 5d, we show the slope K_e of the $\kappa-\psi$ curves at the elastic stage as a function of K_s/E_0 . For better demonstration, K_e is

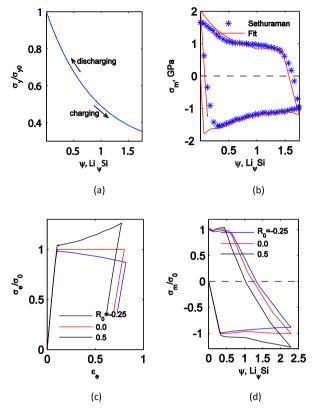


Fig. 4. Dependence of yield strength with lithium fraction. (a) The yield stress σ_y of the electrode material as a function of ψ in the Voce model (see Eq. (24)) during charging and discharging. (b) The numerical results against experimental data from Sethuraman et al. (2010). (c) Mechanical behavior with different yield stress dependence from FE model. (d) The averaged biaxial stress vs. ψ in the film from FE calculations.

normalized by the corresponding slope K_0 of the $\kappa-\psi$ curve from the perfectly bonded film-substrate system. With small interface stiffness and also when $r \to R$, we see K_e/K_0 is apparently affected by the interfacial elastic deformation, which is consistent with previous analysis on how interfacial elasticity changes a multilayer plate's resistance to bending (Peng and Wei, 2016).

4.2. The influence of interfacial strength

Now we discuss the influence of interfacial shear strength on the curvature-capacity relationship. Typically, the bonder materials have low strength. For example, Cu bonder has a shear strength lower than 100 MPa, and a fracture toughness lower than $2 \, \mathrm{J/m^2}$. Meanwhile, both the strength and fracture toughness drop when lithium concentration increases during the charge process (Stournara et al., 2013). In order to discuss the competition between electrode materials' plastic response and interfacial plasticity, we consider the interface of different shear strength. Its effect to the curvature of the electrode during charging-discharging cycles is shown in Fig. 6a. We see the smallest curvature (negative value) increases with the interfacial shear strength. In Fig. 6b, we show the curvature vs. concentration relationship at different positions along the radial direction. The biaxial Cauchy stress σ_m as a function of interfacial shear strength is shown in Fig. 6c. Here the calculation is done at the point with the smallest κ/κ_0 (negative value) in Fig. 6b. The maximum stress increases with the shear strength in the center (r/R=0.1) where its deformation is still elastic. The same trend is also seen at the edge (r/R=0.9) where plastic deformation dominates. However, the behavior is totally different in the transitional region, i.e. $r/R \sim 0.5$, where elastic-plastic deformation coexists.

4.3. Interfacial delamination with plastic dissipation

When shearing of the interface is significant, the interface starts to fail. In Fig. 7a, we show the curvature in the region (r/R=0.8) when different failure separation $\frac{\delta_f}{h_{b0}}$ is used. When $\frac{\delta_f}{h_{b0}}$ is large, the average curvature is the same as that in Fig. 6a. For δ_f smaller than h_{b0} , curvature κ reduces, which is caused by the softening in the interface. For the convenience of better view, we show in Fig. 7b and c the amplified edge of the film-substrate structure. Fig. 7b gives the simulated deformation in the electrode film by using $\frac{\delta_f}{h_{b0}}=0.5$. We see clearly interfacial delamination due to excessive sliding during

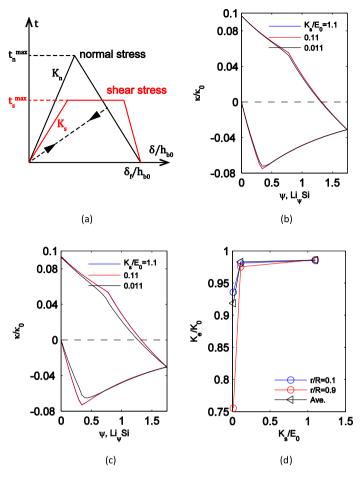


Fig. 5. Curvature evolution with different interfacial stiffness. Here E_0 and K_s are the modulus and the stiffness of the electrode material and the interface, respectively. (a) The constitutive relationship of the cohesive element. (b) & (c) The substrate's curvature vs. ψ from FE calculations at the position r/R = 0.1 and 0.9, respectively. The difference is negligible for $K_s/E_0 > 0.1$. (d) The slope of $\kappa - \psi$ curves in the initial linear stage at different position r/R along the radial direction. Here K_e is the slope of the $\kappa - \psi$ curves in the initial linear stage, and K_0 is the slope of $\kappa - \psi$ curve when the film is perfectly tied to the substrate.

discharge. In Fig. 7c, we show the shear stress evolution in the film electrode during charging and discharging. For better presentation, shear stress in the substrate is not shown. During charging, we see propagation of the maximum shear stress, from $(r/R \sim 0.8)$ to the center of the film $(r/R \sim 0)$. From ii to iv in Fig 7c, we see shear stress relaxation caused by interfacial failure. The opposite shear stress continues to grow and causes continuing crack propagation during discharging. As the failed front moves, the film could be lifted off from the substrate. At the end of the discharging process, a large portion of the interface is delaminated, as shown in Fig. 7c(viii).

5. Conclusions

In this paper, we develop a FE procedure for large plastic deformation to solve the strongly electrochemical-mechanical coupled problem for the high capacity batteries, which can be used to help understand the stress evolution in electrode materials. It may also be used to extract the properties of electrode materials if corresponding experimental stress-capacity data are available for calibration. We apply the model and the numerical method to demonstrate the stress-capacity change in response to different hardening modulus and initial yield stress of the electrode material. By taking the concentration-dependent elastic-plastic behavior of electrode materials (Fig. 1d and e) into account, we are able to fit the stress-capacity curve from experiments. We further show that interfacial delamination has a significant effect on the accuracy of in situ stress measurements. The numerical procedure should be able to, in combination with experimental measurements, reproduce the electrochemical-mechanical process in realistic battery systems. It may also be used to extract material parameters of the electrode material and the interface properties in a film-substrate battery system.

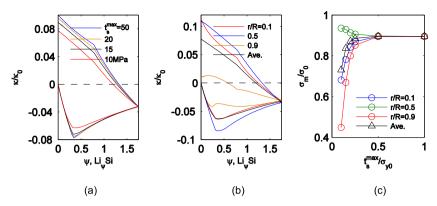


Fig. 6. Curvature evolution with different initial interfacial shear strength t_s^{max} . (a) The average curvature vs. ψ from FE model. (b) The curvature in different radial positions and the averaged value along the radius during a charge/discharge cycle. (c) The calculated biaxial Cauchy stress σ_m in the charging stage using Eq. (22) and the smallest κ/κ_0 in (b).

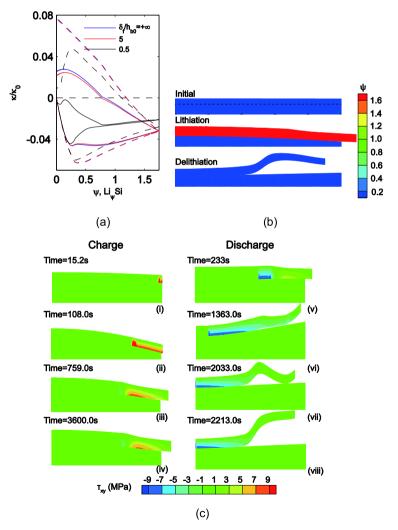


Fig. 7. The influence of the interfacial fracture energy on the substrate's curvature evolution. Here the initial interfacial shear strength is $t_s^{max} = 10$ MPa. (a) The substrate's curvature vs. ψ from FE model at the position of r/R = 0.8 (the solid line) and its average value along the radial direction (the dotted line). (b) FE model's deformation map. Here the structure in the thickness direction has been amplified by a factor of 100. (c) The shear stress map in the film in different charging and discharging stage. The dimension in the thickness direction is 30 times larger than that in the radial direction.

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Supplementary materials

Supplementary material associated with this article can be found, in the online version, at doi:10.1016/j.jmps.2018.04.006.

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